

Point-Identification in Simple Dynamic Binary Outcome Models

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“Fixed” Effects in Discrete Choice Models

- An on-off obsession.
- Past/ongoing/future work with Kyriazidou/de Paula/Toft Hansen.

Combination of Well Understood Topics:

- Simple Panel Data Econometrics.
- Simple Binary Outcome Econometrics.
- Simple Time Series Econometrics.

But we still don't understand it.

Outline

- A bit of survey.
 - ▶ Very, very selective.
- Current work.
 - ▶ Some new results.
 - ▶ Some puzzles.
- Try to convince you that this literature can be useful even if **you** don't care about "fixed" effects models.

Background (Big Picture)

A dependent variable (or vector) in time period t , y_{it} , is modelled as

$$y_{it} \sim f(\cdot | x_i^t, y_i^{t-1}, \alpha_i; \theta)$$

where x_{it} is a vector of explanatory variables and α_i , captures unobserved heterogeneity.

Alternatively (better)

$$y_{it} \sim f\left(\cdot | x_i^T, y_i^{t-1}, \alpha_i; \theta\right).$$

- Interested in identification of θ from the distribution of y_i^T given x_i^T for a small (**finite**) number of time periods, T .
- Nonparametric in the relationship between the heterogeneity term α_i and x_i^T .
- This is sometimes referred to as a “fixed effects” approach.

Disclaimer

Knowing θ in

$$y_{it} \sim f(\cdot | x_i^t, y_i^{t-1}, \alpha_i; \theta)$$

is typically **not** sufficient for calculating counterfactual distributions.

These are typically not point-identified even if θ is.

In principle not too hard to bound “average effects.”

Simplest Case: Static Panel Logit Models

Rasch (1960) considered a static panel data version of the standard logit model,

$$P\left(y_{it} = 1 | x_i^T, y_i^{t-1}, \alpha_i\right) = \frac{\exp(x'_{it}\beta + \alpha_i)}{1 + \exp(x'_{it}\beta + \alpha_i)} = \Lambda(x'_{it}\beta + \alpha_i).$$

In this case, the distribution of (y_{i1}, \dots, y_{iT}) conditional on (x_{i1}, \dots, x_{iT}) and on $\sum_{t=1}^T y_{it}$ does not depend on α_i , but for $T \geq 2$ it does depend on β .

The corresponding **conditional likelihood** can be used to identify and estimate β .

Very (or not) specific to logit assumption.

Much More Interesting Than I Make It Sound

- You might say that the static logit model is (kind of) boring and old-fashioned.
 - ▶ Indeed the conditioning approach dates back to Rasch (1960).
- This setup is at the core of three of the four (much sexier) papers in the econometrics session yesterday.
 - ▶ Botosaru and Muris (2019) uses the insight heavily.
- Recent new paper by Aguirregabiria, Gu, and Luo (2019) use the same conditioning ideas in a structural dynamic model.

2nd Simplest Case: AR(1) Logit Models

$$P(y_{it} = 1 | y_i^{t-1}, \alpha_i) = \frac{\exp(y_{it-1}\gamma + \alpha_i)}{1 + \exp(y_{it-1}\gamma + \alpha_i)}. \quad (1)$$

Conditional on $\left(y_{i1}, \sum_{t=1}^T y_{it}, y_{iT}\right)$, the distribution of (y_{i1}, \dots, y_{iT}) does not depend on α_i , but for $T \geq 4$, it does depend on γ .

The corresponding **conditional likelihood** can therefore be used to identify and estimate γ .

(Cox (1958) and Chamberlain (1985))

3rd Simplest Case: AR(2) Logit Models

$$P(y_{it} = 1 | y_i^{t-1}, \alpha_i, \gamma_{i1}) = \frac{\exp(\gamma_{i1}y_{it-1} + \gamma_2y_{it-2} + \alpha_i)}{1 + \exp(\gamma_{i1}y_{it-1} + \gamma_2y_{it-2} + \alpha_i)}. \quad (2)$$

When the coefficient on y_{it-2} is 0, this corresponds to a Markov switching model.

The sufficient statistic for (γ_{i1}, α_i) with $T \geq 6$ is $(y_{i1}, y_{i2}, s_{i1}, s_{i11}, y_{iT-1}, y_{iT})$, where

$$s_{i1} = \sum_{t=1}^T y_{it} \text{ and } s_{i11} = \sum_{t=2}^T y_{it}y_{it-1}.$$

This can be used to estimate γ_2 (can depend on y_{it-1})

(Chamberlain (1985), Magnac (2000))

There Is a Lot That We Do Not Know

$$P(y_{it} = 1 | y_i^{t-1}, \alpha_i, \gamma_{i1}) = \frac{\exp(\gamma_{i1}y_{it-1} + \gamma_2y_{it-2} + \alpha_i)}{1 + \exp(\gamma_{i1}y_{it-1} + \gamma_2y_{it-2} + \alpha_i)}.$$

What we can learn about the coefficient on y_{it-1} if we restrict it to be constant across individuals: $\gamma_{i1} = \gamma_1$ for all i ?

- As far as I know, this is not known to be identified for any finite T .

Clearly a Toy Model

- But one that we **should** understand!

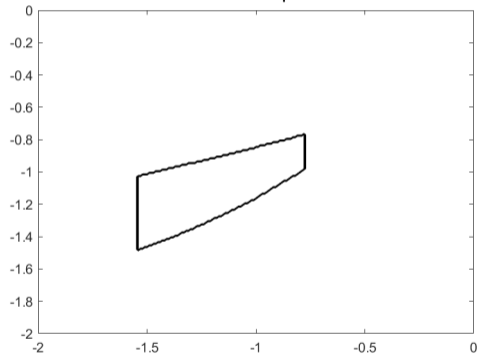
Numerical Strategy

- Assume a data generating process.
- Calculate the “true” probability of every sequence.
- Fix the identified parameters at their actual values.
- For a range of the possibly unidentified parameters, search over distributions of α_j trying to match the “true” probabilities.
 - ▶ Apply discretization. Current work with de Paula improves on this.
- Keep the parameters for which we get a match.

Try a bunch of data generating processes.

Figure: Identified Region when $\gamma_1 = -1$ and $\gamma_2 = -1$

Uniform α_i . T=4



Mixed Normal α_i . T=4

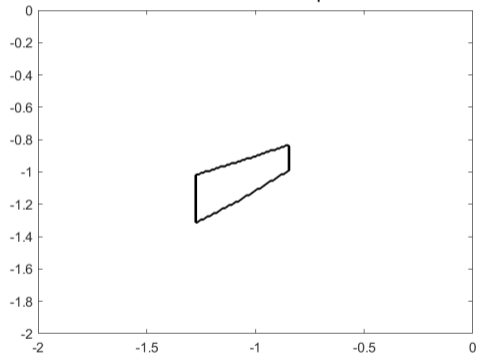


Table: Identified Regions in an AR(2) logit with $T = 5$. $\gamma_1 = \pm 1.5$, $\gamma_2 = \pm 0.7$

(γ_1, γ_2)	Source of identification			
	$(y_3, y_4, y_5 0, 0)$	$(y_3, y_4, y_5 1, 0)$	$(y_3, y_4, y_5 0, 1)$	$(y_3, y_4, y_5 1, 1)$
$\gamma_1 = -1.5$	$\{-1.5000\}$	$\{-1.5000\}$	$\{-1.5000\}$	$\{-1.5000\}$
$\gamma_2 = -0.7$	$[-0.7032, -0.6978]$	$\{-0.7000\}$	$\{-0.7000\}$	$[-0.7044, -0.6971]$
$\gamma_1 = -1.5$	$\{-1.5000\}$	$\{-1.5000\}$	$\{-1.5000\}$	$\{-1.5000\}$
$\gamma_2 = 0.7$	$[0.6985, 0.7010]$	$\{0.7000\}$	$\{0.7000\}$	$[0.6974, 0.7017]$
$\gamma_1 = 1.5$	$\{1.5000\}$	$\{1.5000\}$	$\{1.5000\}$	$\{1.5000\}$
$\gamma_2 = -0.7$	$[-0.7012, -0.6983]$	$\{-0.7000\}$	$\{-0.7000\}$	$[-0.7011, -0.6983]$
$\gamma_1 = 1.5$	$\{1.5000\}$	$\{1.5000\}$	$\{1.5000\}$	$\{1.5000\}$
$\gamma_2 = 0.7$	$[0.6981, 0.7029]$	$\{0.7000\}$	$\{0.7000\}$	$[0.6979, 0.7031]$

Identified?

If so, it seems that the proof is not by standard conditioning arguments.

- With $T = 5$, there are only eight sequences conditional on (y_1, y_2) .

If not, it seems that the identified region is really, **really** small.

This is clearly a “toy” model. But....

Bivariate Models

Following Schmidt and Strauss (1975), consider the bivariate panel data model

$$P\left(y_{1,it} = 1 \mid y_{2,it}, y_{1,i}^{t-1}, y_{2,i}^{t-1}, x_{1,i}^T, x_{2,i}^T, \alpha_{1,i}, \alpha_{2,i}\right) = \Lambda\left(\alpha_{1,i} + x_{1,it}'\beta_1 + \rho y_{2,it}\right)$$

and

$$P\left(y_{2,it} = 1 \mid y_{1,it}, y_{1,i}^{t-1}, y_{2,i}^{t-1}, x_{1,i}^T, x_{2,i}^T, \alpha_{1,i}, \alpha_{2,i}\right) = \Lambda\left(\alpha_{2,i} + x_{2,it}'\beta_2 + \rho y_{1,it}\right).$$

Honoré and Kyriazidou (2018) show that in this case β_1 , β_2 and ρ are identified with $T = 2$.

Entry Games

(with Aureo de Paula; will just give you the flavor of what we are doing)

In a given market in a given period

$$\begin{aligned}y_1 &= 1 \{x_1' \beta - \gamma y_2 + \alpha_1 + \varepsilon_1 > 0\} \\y_2 &= 1 \{x_2' \beta - \gamma y_1 + \alpha_2 + \varepsilon_2 > 0\}\end{aligned}$$

$(\varepsilon_1, \varepsilon_2)$ independent logistic (actually, the distribution does not matter).

These could also be “social interactions.” (Cameiro, Flores, Galasso, Ginja and de Paula (2019)).

With two time periods, and x market specific (so $x_{1jt} = x_{2jt} = x_{jt}$), we have

$$P(N^{j1} = 2) = \frac{\exp(x'_{j1}\beta - \gamma + \alpha_{j1})}{1 + \exp(x'_{j1}\beta - \gamma + \alpha_{j1})} \frac{\exp(x'_{j1}\beta - \gamma + \alpha_{j2})}{1 + \exp(x'_{j1}\beta - \gamma + \alpha_{j2})}$$
$$P(N^{j2} = 2) = \frac{\exp(x'_{j2}\beta - \gamma + \alpha_{j1})}{1 + \exp(x'_{j2}\beta - \gamma + \alpha_{j1})} \frac{\exp(x'_{j2}\beta - \gamma + \alpha_{j2})}{1 + \exp(x'_{j2}\beta - \gamma + \alpha_{j2})}$$

Clearly $P(N^{j1} = 2) \gtrless P(N^{j2} = 2)$ iff $x'_{j1}\beta \gtrless x'_{j2}\beta$.

Look at market where $N^{j1} = 2$ or $N^{j2} = 2$ but not both. Apply maximum score to the event $N^{j1} = 2$ with $x'_{j1} - x'_{j2}$ as explanatory variable.

Logistic does not matter.

- x 's not market specific.
- Conditioning on $x_{2j1} = x_{2j2} = x_{2j}$ (player 2 has the same x in two periods).

In that case,

$$P\left(N^{jt} = 2 \mid \{x_{1js}, x_{2js}\}_{s=1}^2, \alpha_{1j}, \alpha_{2j}\right) = F\left(x'_{1jt}\beta - \gamma + \alpha_{j1}, x'_{2jt}\beta - \gamma + \alpha_{j2}\right)$$

so

$$P\left(N^{j1} = 2 \mid \{x_{1js}, x_{2js}\}_{s=1}^2, \alpha_{1j}, \alpha_{2j}\right) \begin{matrix} \geq \\ \leq \end{matrix} P\left(N^{j2} = 2 \mid \{x_{1js}, x_{2js}\}_{s=1}^2, \alpha_{1j}, \alpha_{2j}\right)$$

iff $x'_{1j1}\beta \begin{matrix} \geq \\ \leq \end{matrix} x'_{1j2}\beta.$

As a result, we can identify and estimate β by conditioning on markets where $N^{j1} = 2$ or $N^{j2} = 2$, but not both.

What about γ ?

- Have not been able to find conditioning arguments that are useful for point-identifying γ .
- Plan to investigate the numerical region for γ using the same general strategy as above.

Step forward in terms of calculation:

- Before we thought of the discretization as an **approximation**.
- We will exploit that there is no loss of generality in assuming that α is discrete with a small (**known**) number of unknown points of support (Theorem).

Hope to prove that values of the points of support can be considered **known**.

Dynamics

Narendranathan, Nickell, and Metcalf (1985):

$$\begin{aligned}y_{1,it} &= 1 \{y_{1,it-1}\gamma_{11} + y_{2,it-1}\gamma_{12} + \alpha_{1,i} + \varepsilon_{1,it} \geq 0\} \\y_{2,it} &= 1 \{y_{1,it-1}\gamma_{21} + y_{2,it-1}\gamma_{22} + \alpha_{2,i} + \varepsilon_{2,it} \geq 0\},\end{aligned}$$

where $\varepsilon_{1,it}$ and $\varepsilon_{2,it}$ are logistic random variables that are independent of each other and independent over time.

All parameters are identified with $T = 4$ periods.

Relax the assumption that $\varepsilon_{1,it}$ and $\varepsilon_{2,it}$ are independent.

Following the motivation in Schmidt and Strauss (1975), Honoré and Kyriazidou (2018) consider a dynamic version of the simultaneous logit model:

$$P\left(y_{1,it} = 1 \mid y_{2,it}, y_{1,i}^{t-1}, y_{2,i}^{t-1}, \alpha_{1,i}, \alpha_{2,i}\right) = \Lambda\left(\alpha_{1,i} + y_{1,it-1}\gamma_{11} + y_{2,it-1}\gamma_{12} + \rho y_{2,it}\right)$$

and

$$P\left(y_{2,it} = 1 \mid y_{1,it}, y_{1,i}^{t-1}, y_{2,i}^{t-1}, \alpha_{1,i}, \alpha_{2,i}\right) = \Lambda\left(\alpha_{2,i} + y_{1,it-1}\gamma_{21} + y_{2,it-1}\gamma_{22} + \rho y_{1,it}\right)$$

When $\rho = 0$, this corresponds to the probabilities in Narendranthan, Nickell, and Metcalf (1985).

Honoré and Kyriazidou (2018) prove that in the dynamic model considered here, $(\gamma_{11}, \gamma_{12}, \gamma_{21}, \gamma_{22})$ is identified with at least four time periods.

However, the conditioning argument that leads to identification of $(\gamma_{11}, \gamma_{12}, \gamma_{21}, \gamma_{22})$, eliminates the parameter ρ along with the heterogeneity terms $\alpha_{1,i}$ and $\alpha_{2,i}$.

Question: What one can say about ρ for some specific data generating processes.

(Footnote: Since ρ drops out, it can be made individual-specific.)

Calculate Identified Region (Not New)

Data

$$p(d_2, \dots, d_T | d_1)$$

Model (function of ρ)

$$\pi(d_2, \dots, d_T | d_1) = \int \Pi_\rho(d_2, \dots, d_T | \alpha, d_1) dH(\alpha | y_1 = d_1)$$

Approximate

$$\pi(d_2, \dots, d_T | d_1) = \sum_k \Pi_\rho(d_2, \dots, d_T | \alpha_k, d_1) h(\alpha_k | y_1 = d_1)$$

ρ in identified region if (for all d_1)

$$p(d_2, \dots, d_T | d_1) = \sum_k \Pi_\rho(d_2, \dots, d_T | \alpha_k, d_1) h(\alpha_k | y_1 = d_1)$$

for some $\{h(\alpha_k | y_1 = d_1)\}$

Let A_j ($j = 1, \dots, 2^{T-1}$) denote all possible sequences of d_2, \dots, d_T , and let

$$Q(g|d_1) = \min_{\{h_k\}, \{v_j\}} \sum_j v_j + v_0 \quad (3)$$

subject to

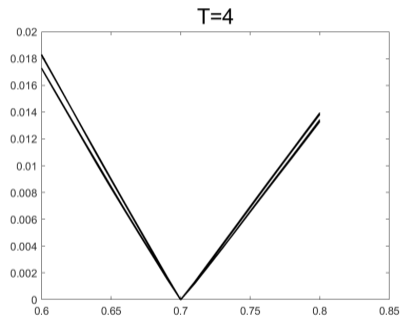
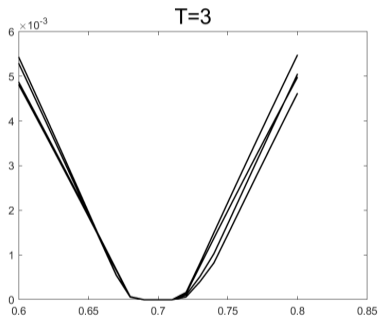
$$\sum_{k=1}^K \Pi_g(A_j | \alpha_k, d_1) h_k + v_j = p(A_j | d_1) \quad (j = 1, \dots, 2^{T-1}),$$

$$\sum_{k=1}^K h_k + v_0 = 1,$$

$$v_j \geq 0,$$

$$h_k \geq 0.$$

Figure: Objective Functions with Negatively Correlated α 's



Useful Even If You Don't Care About Fixed Effects

Paper with Anne Toft (not quite in progress) is about locational choice, but **part of** the paper will estimate a model of educational choice.

$$U_{i0} = \delta_0^1 + x_i' \alpha + \varepsilon_i \quad (\text{no post high school education})$$

$$U_{ip} = \delta_p^1 + x_{ip}' \alpha_p + \varepsilon_{il(p)} + \varepsilon_{is(p)} + \varepsilon_{ip} \quad (\text{program } p \text{ located at } l(p) \text{ in field } s(p))$$

Students rank up to 8 choices.

We will make lots of distributional assumptions

- MLE really complicated.
- Method of simulated moments conceptually easy, but difficult to get to converge.

Suppose ε_{ip} is logistic.

Consider four programs in the choice-set with $I(p_1) = I(p_2)$, $s(p_1) = s(p_2)$, $I(p_3) = I(p_4)$, and $s(p_3) = s(p_4)$. The probability that $U_{ip_1} > U_{ip_3}$ is

$$\begin{aligned} P(U_{ip_1} > U_{ip_3}) \\ = \Lambda \left((\delta_{p_1}^1 + x'_{ip_1} \alpha_{p_1} - \delta_{p_3}^1 - x'_{ip_3} \alpha_{p_3}) + (\varepsilon_{il(p_1)} + \varepsilon_{is(p_1)} - \varepsilon_{il(p_3)} - \varepsilon_{is(p_3)}) \right) \end{aligned}$$

$$\begin{aligned} P(U_{ip_2} > U_{ip_4}) \\ = \Lambda \left((\delta_{p_2}^1 + x'_{ip_2} \alpha_{p_2} - \delta_{p_4}^1 - x'_{ip_4} \alpha_{p_4}) + (\varepsilon_{il(p_2)} + \varepsilon_{is(p_2)} - \varepsilon_{il(p_4)} - \varepsilon_{is(p_4)}) \right) \end{aligned}$$

These are exactly like two logits with the same fixed effect.... This will allow us to easily estimate a lot of the parameters.

Future Steps

Some parameters look like they might be point-identified, even though it seems impossible to prove it using conditioning arguments:

- Try to come up with new identification strategy
- Try to prove non-identification.
 - ▶ Chamberlain (2010) has a result for static non-logit binary outcome models
 - ▶ Working on that with Kyriazidou.
 - ▶ For the AR(1)-logit case, we **seem to have** that at a given $\gamma (\neq 0)$, identification is impossible outside a 2(4)-parameter family. (We think we can do better)

Link to Aguirregabiria, Gu, and Luo (2019).

- - ▶ Much better interpretations in terms of economics.
 - ▶ The same issues come up.

THANKS!