

## EQUILIBRIUM SEARCH WITH TIME-VARYING UNEMPLOYMENT BENEFITS

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### Appendix

*A. Derivation of (12) to (14)*

We start by deriving (12). From (9), when  $\pi(w_s) = 0$ ,

$$w_s = \frac{m(\theta)(1 - \gamma)(x - c) - c\theta(r + \delta)}{m(\theta)(1 - \gamma)}.$$

Equating this to the expression for  $w_s$  given by (5) for the case of risk neutrality gives,

$$\frac{m(\theta)(1 - \gamma)(x - c) - c\theta(r + \delta)}{m(\theta)(1 - \gamma)} = w_b + \frac{(r + \delta)(w_b - b - h)}{\lambda}.$$

Using (8) with  $\pi(w_b) = 0$ ,

$$m(\theta)(x - c) = m(\theta)w_b + c\theta(r + \delta).$$

Substitution then gives

$$\frac{-\gamma c\theta(r + \delta)}{m(\theta)(1 - \gamma)} = \frac{(r + \delta)(w_b - b - h)}{\lambda}.$$

Thus,

$$w_b - b - h = \frac{-\gamma\lambda c\theta}{m(\theta)(1 - \gamma)} = \frac{-[m(\theta)/\lambda + m(\theta)]\lambda c\theta}{m(\theta)[\lambda/\lambda + m(\theta)]} = -c\theta,$$

which verifies (12).

Next, set the expression for  $w_b$  from (12) equal to the one given by (6) with risk neutrality; that is,

$$b + h - c\theta = \frac{[r + \phi m(\theta)](b + h) + \lambda(s + h)}{r + \lambda + \phi m(\theta)}.$$

Solving for  $\phi$  verifies (13).

Finally, from (8)

$$c\theta(r + \delta) = m(\theta)(x - w_b - c).$$

That is,

$$c\theta(r + \delta) = m(\theta)(x - b - h + c\theta - c),$$

which, after rearrangement, verifies (14).

*B. Comparative Statics Derivations*

(a) *Comparative statics for  $\theta$* : Using (14),

$$\frac{\partial \theta}{\partial b} = \frac{m(\theta)}{c[m(\theta) - (r + \delta)] + m'(\theta)[c\theta + (x - c - b - h)]}.$$

The denominator of this expression is positive since, from (14), we have

$$c[m(\theta) - (r + \delta)] = -[m(\theta)/\theta](x - c - b - h) > 0$$

and

$$c\theta + (x - c - b - h) = c\theta(r + \delta)/m(\theta) > 0.$$

Thus,  $\partial\theta/\partial b > 0$ . Since neither  $s$  nor  $\lambda$  enters into (14), we have  $\partial\theta/\partial s = \partial\theta/\partial \lambda = 0$ .

(b) *Comparative statics for  $w_b$* : Using (12),  $\partial w_b/\partial b = 1 - c(\partial\theta/\partial b)$ . That is,

$$\frac{\partial w_b}{\partial b} = \frac{-c(r + \delta) + m'(\theta)[c\theta + (x - c - b - h)]}{c[m(\theta) - (r + \delta)] + m'(\theta)[c\theta + (x - c - b - h)]}.$$

From (14),  $c(r + \delta) = (m(\theta)/\theta)[c\theta + (x - c - b - h)]$ , so by substitution

$$\frac{\partial w_b}{\partial b} = \frac{[(-m(\theta)/\theta) + m'(\theta)][c\theta + (x - c - b - h)]}{c[m(\theta) - (r + \delta)] + m'(\theta)[c\theta + (x - c - b - h)]}.$$

As  $m'(\theta)\theta < m(\theta)$  and  $c\theta + (x - c - b - h) > 0$  we have  $\partial w_b/\partial b < 0$ . Since  $s$  and  $\lambda$  appear in neither (12) nor (14) it follows that  $\partial w_b/\partial s = \partial w_b/\partial \lambda = 0$ .

(c) *Comparative statics for  $w_s$* : From (5'),

$$\begin{aligned} \frac{\partial w_s}{\partial b} &= \left( \frac{r + \delta + \lambda}{\lambda} \right) \frac{\partial w_b}{\partial b} - \frac{r + \delta}{\lambda} < 0 \text{ and} \\ \frac{\partial w_s}{\partial \lambda} &= \frac{(b + h - w_b)(r + \delta)}{\lambda^2} = \frac{c\theta(r + \delta)}{\lambda^2} > 0. \end{aligned}$$

Finally,  $\partial w_s/\partial s = 0$ .

(d) *Comparative statics for  $\phi$* : From (13),

$$\frac{\partial \phi}{\partial b} = \frac{\lambda}{c\theta m(\theta)} + \frac{\partial \phi}{\partial \theta} \frac{\partial \theta}{\partial b},$$

where

$$\frac{\partial \phi}{\partial \theta} = \frac{c\theta m(\theta)[-c(r + \lambda)] - [\lambda(b - s) - c\theta(r + \lambda)][cm(\theta) + c\theta m'(\theta)]}{[c\theta m(\theta)]^2}$$

and

$$\frac{\partial \theta}{\partial b} = \frac{m(\theta)}{c[m(\theta) - (r + \delta)] + m'(\theta)[c\theta + (x - c - b - h)]}.$$

We thus have

$$\frac{\partial \phi}{\partial b} = \frac{\lambda}{c\theta m(\theta)} - \frac{m(\theta)\lambda(b - s) + \theta m'(\theta)[\lambda(b - s) - c\theta(r + \lambda)]}{c\theta^2 m(\theta)\{c[m(\theta) - (r + \delta)] + m'(\theta)[c\theta + (x - c - b - h)]\}}.$$

Multiplying both sides by  $c\theta m(\theta)$ , the sign of  $\partial\phi/\partial b$  is the same as that of

$$\lambda - \frac{m(\theta)\lambda(b-s) + \theta m'(\theta)[\lambda(b-s) - c\theta(r+\lambda)]}{c\theta[m(\theta) - (r+\delta)] + m'(\theta)\theta[c\theta + (x-c-b-h)]}.$$

Since the denominator of the fraction is positive, the sign of  $\partial\phi/\partial b$  is the same as that of

$$\begin{aligned} & \lambda c\theta[m(\theta) - (r+\delta)] + \lambda m'(\theta)\theta[c\theta + (x-c-b-h)] \\ & - m(\theta)\lambda(b-s) - \theta m'(\theta)[\lambda(b-s) - c\theta(r+\lambda)]. \end{aligned}$$

From (14),  $x - c - b - h = [c\theta(r+\delta)/m(\theta)] - c\theta$ ; thus, the sign of  $\partial\phi/\partial b$  is the same as that of

$$\lambda m(\theta)[c\theta - (b-s)] - \lambda c\theta(r+\delta) \left[ 1 - \frac{m'(\theta)\theta}{m(\theta)} \right] - \theta m'(\theta)[\lambda(b-s) - c\theta(r+\lambda)].$$

The first and third of these three terms are negative by (13); specifically, by the condition  $\phi > 0$ . The second term is negative by  $m'(\theta)\theta < m(\theta)$ . We thus have  $\partial\phi/\partial b < 0$ .

Next,

$$\frac{\partial\phi}{\partial\lambda} = \frac{b-s-c\theta}{c\theta m(\theta)} > 0$$

since, again from (13),  $b-s-c\theta > 0$ .

Finally,

$$\frac{\partial\phi}{\partial s} = -\frac{\lambda}{c\theta m(\theta)} < 0.$$

(e) *Comparative statics for  $\gamma$* : From (10),

$$\frac{\partial\gamma}{\partial\theta} = \frac{\lambda m'(\theta)}{[\lambda + m(\theta)]^2} > 0.$$

Then  $\partial\gamma/\partial\lambda = -m(\theta)/[\lambda + m(\theta)]^2 < 0$ , and the rest of the derivatives of  $\gamma$  have the same signs as the partials of  $\theta$  with respect to the various parameters. Specifically,  $\partial\gamma/\partial b > 0$  and  $\partial\gamma/\partial s = 0$ .

(f) *Comparative statics for  $u$* : From (11),

$$\frac{\partial u}{\partial b} = \frac{\partial u}{\partial\phi m(\theta)} \frac{\partial\phi m(\theta)}{\partial b} + \frac{\partial u}{\partial\gamma} \frac{\partial\gamma}{\partial b},$$

where

$$\frac{\partial u}{\partial\phi m(\theta)} = \frac{-\delta\gamma}{\{\delta + \gamma[\phi m(\theta) + \lambda]\}^2} < 0$$

and

$$\frac{\partial u}{\partial\gamma} = \frac{-\delta(\phi m(\theta) + \lambda)}{\{\delta + \gamma[\phi m(\theta) + \lambda]\}^2} < 0.$$

Let  $\Psi = \delta/\{\delta + \gamma[\phi m(\theta) + \lambda]\}^2 > 0$ . Then, we have

$$\frac{\partial u}{\partial b} = -\Psi \left\{ \gamma \frac{\partial\phi m(\theta)}{\partial b} + [\phi m(\theta) + \lambda] \frac{\partial\gamma}{\partial b} \right\}.$$

Next from (13) we have

$$\phi m(\theta) = \frac{\lambda(b-s)}{c\theta} - (r + \lambda)$$

so

$$\frac{\partial \phi m(\theta)}{\partial b} = \frac{\lambda}{c\theta} - \frac{\lambda(b-s)}{c\theta^2} \frac{\partial \theta}{\partial b} = \frac{\lambda}{c\theta} \left[ 1 - \frac{(b-s)}{\theta} \frac{\partial \theta}{\partial b} \right].$$

From above,

$$\frac{\partial \gamma}{\partial b} = \frac{\lambda m'(\theta)}{[\lambda + m(\theta)]^2} \frac{\partial \theta}{\partial b} > 0.$$

Thus,

$$\frac{\partial u}{\partial b} = -\lambda \Psi \left( \frac{\gamma}{c\theta} + \frac{\partial \theta}{\partial b} \left\{ \frac{m'(\theta)[\phi m(\theta) + \lambda]}{[\lambda + m(\theta)]^2} - \frac{\gamma(b-s)}{c\theta^2} \right\} \right).$$

Since

$$\frac{m'(\theta)[\phi m(\theta) + \lambda]}{[\lambda + m(\theta)]^2} = \frac{\gamma m'(\theta)[\phi m(\theta) + \lambda]}{m(\theta)[\lambda + m(\theta)]},$$

we have

$$\frac{\partial u}{\partial b} = -\frac{\lambda \gamma}{c\theta} \Psi \left( 1 + \frac{\partial \theta}{\partial b} \left\{ \frac{m'(\theta)[\phi m(\theta) + \lambda]c\theta}{m(\theta)[\lambda + m(\theta)]} - \frac{(b-s)}{\theta} \right\} \right).$$

Then,

$$\text{sign} \left( \frac{\partial u}{\partial b} \right) = -\text{sign} \left( 1 + \frac{\partial \theta}{\partial b} \left\{ \frac{m'(\theta)[\phi m(\theta) + \lambda]c\theta}{m(\theta)[\lambda + m(\theta)]} - \frac{(b-s)}{\theta} \right\} \right).$$

Without imposing more restrictions on  $m(\theta)$ , this latter sign is indeterminate.

Next, since  $\partial \gamma / \partial s = \partial \theta / \partial s = 0$ , we have

$$\frac{\partial u}{\partial s} = \frac{\partial u}{\partial \phi} \frac{\partial \phi}{\partial s}.$$

Since

$$\frac{\partial u}{\partial \phi} = \frac{-\delta \gamma m(\theta)}{\{\delta + \gamma[\phi m(\theta) + \lambda]\}^2} < 0$$

and, as shown above,  $\partial \phi / \partial s < 0$ , we have  $\partial u / \partial s > 0$ .

Finally, using  $\partial \theta / \partial \lambda = 0$ , we have

$$\frac{\partial u}{\partial \lambda} = \frac{\partial u}{\partial \phi} \frac{\partial \phi}{\partial \lambda} + \frac{\partial u}{\partial \gamma} \frac{\partial \gamma}{\partial \lambda} - \frac{\delta \gamma}{\{\delta + \gamma[\phi m(\theta) + \lambda]\}^2}.$$

The final term is the direct effect of  $\lambda$  on  $u$ . Substitution gives,

$$\begin{aligned} \frac{\partial u}{\partial \lambda} = & - \left( \frac{\delta \gamma m(\theta)}{\{\delta + \gamma[\phi m(\theta) + \lambda]\}^2} \right) \left[ \frac{b-s-c\theta}{c\theta m(\theta)} \right] \\ & + \left( \frac{\delta[\phi m(\theta) + \lambda]}{\{\delta + \gamma[\phi m(\theta) + \lambda]\}^2} \right) \left\{ \frac{m(\theta)}{[\lambda + m(\theta)]^2} \right\} - \frac{\delta \gamma}{\{\delta + \gamma[\phi m(\theta) + \lambda]\}^2}. \end{aligned}$$

Or,

$$\frac{\partial u}{\partial \lambda} = -\Psi \left\{ \frac{\gamma(b-s-c\theta)}{c\theta} - \frac{m(\theta)[\phi m(\theta) + \lambda]}{[\lambda + m(\theta)]^2} + \gamma \right\}.$$

The sign of  $\partial u/\partial \lambda$  is the same as that of

$$-\frac{\gamma(b-s)}{c\theta} + \frac{m(\theta)[\phi m(\theta) + \lambda]}{[\lambda + m(\theta)]^2}.$$

Using (10) and (13) for  $\gamma$  and  $\phi$ , the sign of  $\partial u/\partial \lambda$  is the same as that of

$$\frac{-m(\theta)/\lambda + m(\theta)(b-s)}{c\theta} + \frac{m(\theta)[\lambda(b-s) - c\theta(r+\lambda)/c\theta + \lambda]}{[\lambda + m(\theta)]^2} = \frac{-m(\theta)[(b-s)m(\theta) + c\theta r]}{c\theta[\lambda + m(\theta)]^2} < 0.$$

Thus,  $\partial u/\partial \lambda < 0$ .